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1. Attitude control of hopping robot using angular momentum

Morita, Y.; Ohnishi, K.;
Industrial Technology, 2003 IEEE International Conference on
Volume 1, 10-12 Dec. 2003 Page(s):173 - 178 Vol.1

IEEE CNF

2. Proceedings of IEEE International Conference on Control and Applications:

Control Applications, 1994., Proceedings of the Third IEEE Conference on
24-26 Aug. 1994

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